

LESSON 5 - 14 APRIL 2021

4. THE EULER-LAGRANGE EQUATION

After the many examples seen so far, we look at the general theory for the minimization of integral functionals

$$F(u) := \int_a^b L(x, u(x), u'(x)) dx$$

where $L: [a, b] \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$, $L = L(x, s, p)$, is the **LAGRANGIAN** and $u: [a, b] \rightarrow \mathbb{R}$. We want to make sufficient assumptions on L so that F admits the first variation δF in some appropriate domain of definition. Specifically, we have:

THEOREM 4.1 Suppose that $L: [a, b] \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ is continuous, and continuously partially differentiable w.r.t to the variables s, p . Let $X \subseteq C^1([a, b])$ be an affine space, with reference vector space $V \subseteq C^1([a, b])$. Define $F: X \rightarrow \mathbb{R}$ by setting

$$F(u) := \int_a^b L(x, u(x), u'(x)) dx$$

Then F is Gateaux differentiable at all points $u \in X$ and all directions $v \in V$, with

$$F'_g(u)(v) = \int_a^b L_s(x, u, u') v + L_p(x, u, u') v' dx$$

with $L_s := \partial_s L$, $L_p := \partial_p L$. In particular $\delta F(u, v)$ exists, with

$$\delta F(u, v) = \int_a^b L_s(x, u, u') v + L_p(x, u, u') v' dx$$

NOTE: Here $C^1[a,b]$ is equipped with the norm $\|u\| := \|u\|_\infty + \|u'\|_\infty$.

Proof Let $u \in X, v \in V$. As X is affine space over V , then $u + tv \in X, \forall t \in \mathbb{R}$.

Then

$$(*) \quad \frac{F(u+tv) - F(u)}{t} = \int_a^b \underbrace{\frac{L(x, u+tv, \dot{u}+t\dot{v}) - L(x, u, \dot{u})}{t}}_{=: \Lambda(t, x)} dx$$

Now suppose $|t| \leq \varepsilon$. Then

$$\Lambda(t, x) = \frac{1}{t} \int_0^t \left\{ \frac{d}{d\tau} L(x, u(x) + \tau v(x), \dot{u}(x) + \tau \dot{v}(x)) \right\} d\tau$$

AS L diff. in $S, p \rightarrow = \frac{1}{t} \int_0^t \left\{ L_S(x, u + \tau v + \dot{u} + \tau \dot{v}) v + L_p(x, u + \tau v, \dot{u} + \tau \dot{v}) \dot{v} \right\} d\tau$

Adding and subtracting $\rightarrow = L_S(x, u, \dot{u}) v + L_p(x, u, \dot{u}) \dot{v}$

$$+ \frac{1}{t} \int_0^t \left\{ L_S(x, u + \tau v, \dot{u} + \tau \dot{v}) v - L_S(x, u, \dot{u}) v \right\} d\tau \quad (=: R_1(t, x))$$

$$+ \frac{1}{t} \int_0^t \left\{ L_p(x, u + \tau v, \dot{u} + \tau \dot{v}) \dot{v} - L_p(x, u, \dot{u}) \dot{v} \right\} d\tau \quad (=: R_2(t, x))$$

Thus, by (*),

$$\begin{aligned} \frac{F(u+tv) - F(u)}{t} &= \int_a^b \Lambda(t, x) dx \\ &= \int_a^b L_S(x, u, \dot{u}) v + L_p(x, u, \dot{u}) \dot{v} dx + \int_a^b R_1(t, x) dx + \int_a^b R_2(t, x) dx \end{aligned}$$

To see that F is G^2 twice diff it is sufficient to show that

$$\lim_{t \rightarrow 0} \int_a^b R_j(t, x) dx = 0, \quad \text{for } j=1, 2.$$

To this end, notice that, as $u, v \in C^1[a, b]$, then

$$K := \left\{ (x, u(x) + \tau v(x), \dot{u}(x) + \tau \dot{v}(x)) \mid x \in [a, b], |\tau| \leq \frac{\varepsilon}{2} \right\}$$

is compact in $[a, b] \times \mathbb{R} \times \mathbb{R}$. As L_S is continuous on $[a, b] \times \mathbb{R} \times \mathbb{R}$, then in particular it is uniformly continuous on K (continuous on compact \Rightarrow u.c.).
 Then $\forall \tilde{\varepsilon} > 0, \exists \delta > 0$ s.t.

$$\left| L_S(x, u(x) + \tau v(x), \dot{u}(x) + \tau \dot{v}(x)) - L_S(x, u(x), \dot{u}(x)) \right| < \tilde{\varepsilon} \quad (*)$$

for all $x \in [a, b]$ and $|\tau| \leq \frac{\varepsilon}{2}$, such that $|\tau| (|v(x)| + |\dot{v}(x)|) < \delta$.
 The last condition is fulfilled for τ s.t.

$$|\tau| < \min \left\{ \frac{\varepsilon}{2}, \frac{\delta}{\|v\|} \right\} \quad (B)$$

Therefore let $\hat{\varepsilon} > 0$ be arbitrary and fix $\tilde{\varepsilon} > 0$ s.t.

$$\tilde{\varepsilon} < \frac{\hat{\varepsilon}}{\|v\|} \quad (**)$$

Let also $\tilde{\delta} := \min \left\{ \frac{\varepsilon}{2}, \frac{\delta}{\|v\|} \right\}$. Then for $|t| < \tilde{\delta}$ we have

$$|R_2(t, x)| \leq \frac{1}{|t|} \int_0^t |L_S(x, u + \tau v, \dot{u} + \tau \dot{v}) - L_S(x, u, \dot{u})| d\tau |v(x)|$$

$$\left(\begin{array}{l} \text{by } (*), \text{ as} \\ |\tau| \leq |t| < \tilde{\delta}, \text{ so} \\ \text{that (B) holds} \end{array} \right) \leq \frac{\|v\|}{|t|} \int_0^t \tilde{\varepsilon} d\tau = \|v\| \tilde{\varepsilon} < \hat{\varepsilon} \quad (\text{by } (**))$$

As $\hat{\varepsilon}$ is arbitrary, and $\tilde{\delta}$ does not depend on x , we conclude

$$\lim_{t \rightarrow 0} \sup_{x \in [a, b]} |R_2(t, x)| = 0.$$

By similar arguments also $\lim_{t \rightarrow 0} \sup_{x \in [a, b]} |R_2(t, x)| = 0$.

Then $\int_a^b R_1(t, x) dx \rightarrow 0$ as $t \rightarrow 0$. Taking the limit in

$$\frac{F(u+t\vartheta) - F(u)}{t} = \int_a^b L_s(x, u, \dot{u}) \vartheta + L_p(x, u, \dot{u}) \ddot{\vartheta} dx + \int_a^b R_1(t, x) dx + \int_a^b R_2(t, x) dx$$

yields that

$$F'_g(u)(\vartheta) = \int_a^b L_s(x, u, \dot{u}) \vartheta + L_p(x, u, \dot{u}) \ddot{\vartheta} dx,$$

as claimed. Now just recall that for affine spaces which are also normed,

$$\delta F(u, \vartheta) := \lim_{t \rightarrow 0} \frac{F(u+t\vartheta) - F(u)}{t}$$

(see REMARK 2.5). This concludes. \square

DEFINITION 4.2 In the setting of THEOREM 4.1, we call

$$\delta F(u, \vartheta) = \int_a^b L_s(x, u, \dot{u}) \vartheta + L_p(x, u, \dot{u}) \ddot{\vartheta} dx$$

the **FIRST INTEGRAL FORM** of the **FIRST VARIATION**.

CASE OF DIRICHLET BOUNDARY CONDITIONS

Assume $L: [a, b] \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ continuous, and continuously diff. in s, p .

Let

$$X = \{ u \in C^1[a, b] \mid u(a) = \alpha, u(b) = \beta \}$$

which is an affine space over

$$V = \{ \vartheta \in C^1[a, b] \mid \vartheta(a) = \vartheta(b) = 0 \}.$$

Then we can apply THEOREM 4.1, and $\delta F(u, \vartheta)$ is given by $\textcircled{*}$.

Assume also that

$$L \in C^2([a, b] \times \mathbb{R} \times \mathbb{R}), \quad u \in C^2[a, b] \cap X$$

Then the second term in $(*)$ can be integrated by parts:

$$\begin{aligned} \int_a^b L_p(x, u, \dot{u}) \delta v \, dx &= L_p(x, u, \dot{u}) \delta v \Big|_a^b - \int_a^b (L_p(x, u, \dot{u}))' \delta v(x) \, dx \\ &= - \int_a^b (L_p(x, u, \dot{u}))' \delta v(x) \, dx \quad (\text{as } \delta v(a) = \delta v(b) = 0) \end{aligned}$$

Therefore $(*)$ reads

$$(**) \quad \delta F(u, \delta v) = \int_a^b \left\{ L_s(x, u, \dot{u}) - (L_p(x, u, \dot{u}))' \right\} \delta v(x) \, dx$$

Note that, in the above assumptions, we can explicitly compute

$$(L_p(x, u, \dot{u}))' = L_{px}(x, u, \dot{u}) + L_{ps}(x, u, \dot{u}) \dot{u} + L_{pp}(x, u, \dot{u}) \ddot{u}$$

DEFINITION 4.3 $(**)$ is called the **SECOND INTEGRAL FORM** of the **FIRST VARIATION**

Assume in addition that u minimizes F over X .

Then by **REMARK 3.7** we know that $\delta F(u, \delta v) = 0$, $\forall \delta v \in V$. Note that $C_c^\infty(a, b) \subseteq V$. Hence we can apply the **FLCV (LEMMA 3.4)** to $(**)$ (equated to zero), and obtain

$$(***) \quad [L_p(x, u, \dot{u})]' = L_s(x, u, \dot{u})$$

Note that, in addition to $(***)$, u satisfies also the **DIRICHLET BC** imposed in X , that is,

$$u(a) = \alpha, \quad u(b) = \beta$$

DEFINITION 4.4

*** is called **EULER-LAGRANGE EQUATION**
in **DIFFERENTIAL FORM**.

We therefore have proven the following theorem.

THEOREM 4.5

Let $L: [a, b] \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ be continuous and continuously partially differentiable in s, p .

Define

$$X := \{ u \in C^1[a, b] \mid u(a) = \alpha, u(b) = \beta \}$$

$$V := \{ v \in C^1[a, b] \mid v(a) = v(b) = 0 \}$$

Define the functional $F: X \rightarrow \mathbb{R}$ s.t.

$$F(u) := \int_a^b L(x, u, \dot{u}) dx$$

(1) If $u \in X$ minimizes F over X , then u solves the **ELE in INTEGRAL FORM**:

$$\int_a^b L_s(x, u, \dot{u}) v + L_p(x, u, \dot{u}) \dot{v} dx = 0$$

for all $v \in V$.

(2) Assume in addition $L \in C^2([a, b] \times \mathbb{R} \times \mathbb{R})$.

If $u \in X \cap C^2[a, b]$ minimizes F over X , then u solves the **ELE in DIFFERENTIAL FORM**:

$$\left\{ \begin{array}{l} \frac{d}{dx} [L_p(x, u(x), \dot{u}(x))] = L_s(x, u(x), \dot{u}(x)), \quad \forall x \in (a, b) \\ u(a) = \alpha, \quad u(b) = \beta \end{array} \right.$$

THE CASE OF NEUMANN BOUNDARY CONDITIONS

Again, suppose $L: [a, b] \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ is continuous and continuously diff. in s, p . Define

$$X = \{ u \in C^1[a, b] \mid u(a) = \alpha \}$$

which is affine over

$$V = \{ v \in C^1[a, b] \mid v(a) = 0 \}.$$

We can then apply THEOREM 4.1 to obtain the FIRST INTEGRAL FORM of the FIRST VARIATION:

$$(*) \quad \delta F(u, v) = \int_a^b L_s(x, u, \dot{u}) v + L_p(x, u, \dot{u}) \dot{v} \, dx$$

Assume in addition that

$$L \in C^2([a, b] \times \mathbb{R} \times \mathbb{R}), \quad u \in C^2[a, b] \cap X.$$

Then the second term in $(*)$ can be integrated by parts

$$\begin{aligned} \int_a^b L_p(x, u, \dot{u}) \dot{v} \, dx &= L_p(x, u, \dot{u}) v \Big|_a^b - \int_a^b (L_p(x, u, \dot{u}))' v(x) \, dx \\ &= L_p(b, u(b), \dot{u}(b)) v(b) - \int_a^b [L_p(x, u, \dot{u})]' v \, dx \end{aligned}$$

obtaining the SECOND INTEGRAL FORM of the FIRST VARIATION:

$$(**) \quad \delta F(u, v) = \int_a^b \{ L_s(x, u, \dot{u}) - [L_p(x, u, \dot{u})]' \} v \, dx + L_p(b, u(b), \dot{u}(b)) v(b)$$

Assume now that u is also a minimizer. Then by REMARK 3.7 we have $\delta F(u, \nu) = 0, \forall \nu \in V$. In particular we can test for

$$\nu \in V \text{ s.t. } \nu(b) = 0$$

to obtain

$$\int_a^b \{ L_S(x, u, \dot{u}) - [L_P(x, u, \dot{u})]' \} \nu \, dx = 0, \forall \nu \in C^1[a, b] \text{ s.t. } \nu(a) = \nu(b) = 0.$$

Then by FLCV we obtain the EULER-LAGRANGE EQUATION in DIFF. FORM:

$$\boxed{[L_P(x, u, \dot{u})]' = L_S(x, u, \dot{u})}$$

Now, the first boundary condition to pair to $\boxed{***}$ is already given in X :

$$u(a) = \alpha$$

For the second BC, just test $\boxed{**}$ against $\nu \in V$ s.t. $\nu(b) \neq 0$, and recall $\boxed{***}$, to get

Taking $\nu \in V$
s.t. $\nu(b) \neq 0$

$$L_P(b, u(b), \dot{u}(b)) \nu(b) = 0, \forall \nu \in V \Rightarrow L_P(b, u(b), \dot{u}(b)) = 0$$

which is a NEUMANN BOUNDARY CONDITION.

NOTE If we took $X = V = C^1[a, b]$ in the above example, we would have obtained their minimizers $u \in C^2[a, b] \cap X$ satisfy $\boxed{***}$ with two NEUMANN BC

$$L_P(a, u(a), \dot{u}(a)) = L_P(b, u(b), \dot{u}(b)) = 0$$

To summarize, we have proven the following Theorem:

THEOREM 4.6 Let $L: [a, b] \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ be continuous and continuously partially differentiable w.r.t s, p .

Define sets

$$X := \{ u \in C^1[a, b] \mid u(a) = \alpha \}$$

$$V := \{ v \in C^1[a, b] \mid v(a) = 0 \}$$

Define $F: X \rightarrow \mathbb{R}$ by

$$F(u) := \int_a^b L(x, u, u') dx$$

(1) Suppose u minimizes F over X . Then u solves the ELE in INTEGRAL FORM:

$$\int_a^b L_s(x, u, u') v + L_p(x, u, u') v' dx = 0, \quad \forall v \in V$$

(2) Suppose in addition $L \in C^2([a, b] \times \mathbb{R} \times \mathbb{R})$, and that $u \in X \cap C^2[a, b]$ minimizes F over X . Then u solves

ELE in DIFFERENTIAL FORM:

$$\begin{cases} \frac{d}{dx} [L_p(x, u(x), u'(x))] = L_s(x, u(x), u'(x)), & \forall x \in (a, b) \\ u(a) = \alpha, \quad L_p(b, u(b), u'(b)) = 0 \end{cases}$$

ELE IN ERDMANN FORM

Consider the special case of Lagrangians not depending on x , i.e.,

$$F(u) = \int_a^b L(u, \dot{u}) dx, \quad L: \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$$

with $F: X \rightarrow \mathbb{R}$, $X \subseteq C^1[a, b]$ affine space over $V \subseteq C^1[a, b]$.

As done previously, if $L \in C^2(\mathbb{R} \times \mathbb{R})$ and $u \in C^2[a, b] \cap X$ minimizes F over X , the ELE reads

$$(*) \quad [L_p(u, \dot{u})]' = L_s(u, \dot{u}), \quad \forall x \in (a, b)$$

Multiplying by \dot{u} yields

$$(**) \quad [L_p(u, \dot{u})]' \dot{u} = L_s(u, \dot{u}) \dot{u}$$

Now the LHS is

$$[L_p(u, \dot{u})]' \dot{u} = [L_p(u, \dot{u}) \dot{u}]' - L_p(u, \dot{u}) \ddot{u}$$

so that, from $(**)$

$$[L_p(u, \dot{u}) \dot{u}]' \stackrel{\text{by } (**)}{=} L_s(u, \dot{u}) \dot{u} + L_p(u, \dot{u}) \ddot{u} \stackrel{\text{by direct calculation}}{=} [L(u, \dot{u})]'$$

Therefore

$$L_p(u, \dot{u}) \dot{u} = L(u, \dot{u}) + \text{constant}$$

ELE im ERDMANN
FORM

REMARK 4.5 ELE and ELE-ERDMANN are not equivalent. It holds:

(1) If u satisfies ELE $\Rightarrow u$ satisfies ELE-ERDMANN

(We just proved this)

(2) If u satisfies ELE-ERDMANN $\Rightarrow u$ satisfies ELE in the points $x \in [a, b]$ s.t. $u'(x) \neq 0$

(To show this, just go backwards in the above calculation)

ELE FOR GENERAL LAGRANGIANS

HIGHER ORDER

$X \subseteq C^k[a, b]$ affine space over $V \subseteq C^k[a, b]$, $L: [a, b] \times \mathbb{R} \times \mathbb{R}^k \rightarrow \mathbb{R}$

$L = L(x, s, p_1, \dots, p_k)$, $F: X \rightarrow \mathbb{R}$ defined by:

$$F(u) := \int_a^b L(x, u, u', u'', \dots, u^{(k)}) dx$$

Assume L is continuous and continuously differentiable w.r.t. s, p_1, \dots, p_k .

Analogously to THEOREM 4.1, one can compute the Gâteaux derivative of F and obtain the **FIRST INTEGRAL FORM OF THE FIRST VARIATION**

$$\delta F(u, v) = \int_a^b L_s(x, u, \dots, u^{(k)}) v + \sum_{i=1}^k L_{p_i}(x, u, \dots, u^{(k)}) v^{(i)} dx$$

Assume now that $L \in C^2([a,b] \times \mathbb{R} \times \mathbb{R}^k)$, $u \in C^{k+1}[a,b]$, and $v \in V$ is s.t. $v^{(i)}(a) = v^{(i)}(b) = 0$ for all $i=0, \dots, k-1$. Integrating \int by parts we get the **SECOND INTEGRAL FORM** of the **FIRST VARIATION**

$$\delta F(u, v) = \int_a^b \left\{ L_S(x, u, \dots, u^{(k)}) + \sum_{i=1}^k (-1)^i \frac{d^i}{dx^i} L_{p_i}(x, u, \dots, u^{(k)}) \right\} v \, dx$$

Finally, if in addition u is a minimizer, then $\delta F(u, v) = 0$, and by the FLCV we get the **ELE in DIFFERENTIAL FORM**

$$\sum_{i=1}^k (-1)^{i+1} \frac{d^i}{dx^i} L_{p_i}(x, u, \dots, u^{(k)}) = L_S(x, u, \dots, u^{(k)}), \quad \forall x \in (a, b)$$

MORE UNKNOWNNS

$X \subseteq C^1[a,b]$ affine space over $V \subseteq C^1[a,b]$, $L: [a,b] \times \mathbb{R}^k \times \mathbb{R}^k \rightarrow \mathbb{R}$,

$L = L(x, s_1, \dots, s_k, p_1, \dots, p_k)$, $F: \underbrace{X \times \dots \times X}_{k \text{ times}} \rightarrow \mathbb{R}$ defined by

$$F(u_1, \dots, u_k) := \int_a^b L(x, u_1, \dots, u_k, \dot{u}_1, \dots, \dot{u}_k) \, dx$$

Assume L is continuous and continuously differentiable in $s_1, \dots, s_k, p_1, \dots, p_k$.

Analogously to THEOREM 4.1, one can compute the Gâteaux derivative of F and obtain the **FIRST INTEGRAL FORM of the FIRST VARIATION**

$$\delta F(u, v) = \int_a^b \sum_{i=1}^k \left[L_{s_i}(x, u, \dot{u}) v_i + L_{p_i}(x, u, \dot{u}) \dot{v}_i \right] dx \quad (*)$$

where $u = (u_1, \dots, u_k) \in X^k$, $v = (v_1, \dots, v_k) \in X^k$.

Suppose in addition that $L \in C^2([a, b] \times \mathbb{R}^k \times \mathbb{R}^k)$, $u_i \in C^2[a, b] \cap X$ and that $v_i \in V$ are s.t. $v_i(a) = v_i(b) = 0$, for all $i = 1, \dots, k$. Then we can integrate $(*)$ by parts to get the **SECOND INTEGRAL FORM of the FIRST VARIATION**

$$\delta F(u, v) = \int_a^b \sum_{i=1}^k \left[L_{s_i}(x, u, \dot{u}) - L_{p_i}(x, u, \dot{u})' \right] v_i dx$$

Finally, taking $u \in X^k$ minimum of F and $v_1 \in C_0^\infty(a, b)$, $v_2 = v_3 = \dots = v_k = 0$ and applying FLCV, we get

$$L_{p_1}(x, u, \dot{u})' = L_{s_1}(x, u, \dot{u})$$

Similarly, by taking the other components of v to be zero, except for one, we obtain the **ELE in DIFFERENTIAL FORM**

$$L_{p_i}(x, u, \dot{u})' = L_{s_i}(x, u, \dot{u}), \quad i = 1, \dots, k, \quad \forall x \in (a, b)$$

which in this case is a SYSTEM of k ODES of ORDER 2.